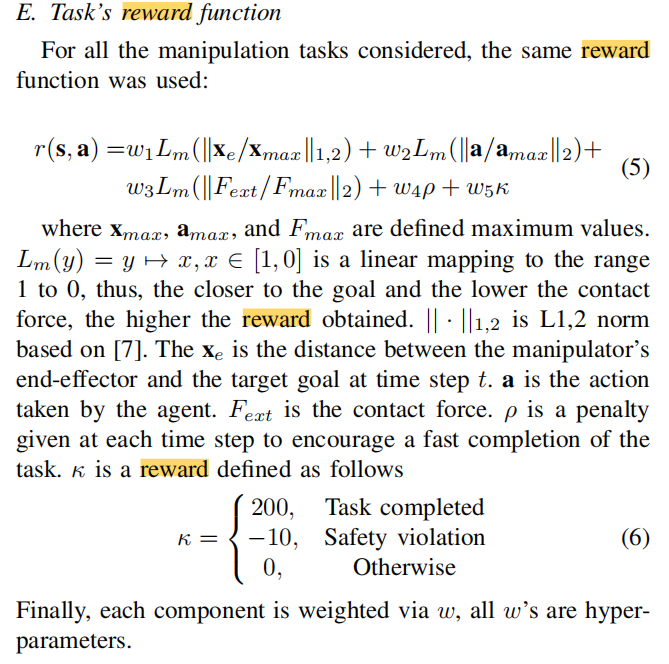
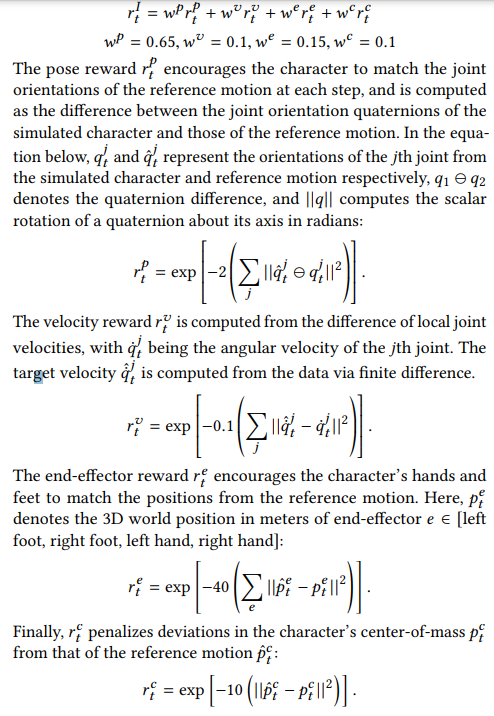
Learning force control for contact-rich manipulation tasks with rigid position-controlled robots(高精度装配)

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1. DeepMimic： Example guided deep reinforcement learning of physics based character skills

人形机器人技能学习



1. DDPGfD(装配问题)

